# Wavelet-based numerical method for solving <br> fractional integro-differential equation with a weakly singular kernel 

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## Article Info

## Article history:

Received 10 November 2016
Accepted 13 February 2017
Available online 01 July 2017
Communicated by Asghar
Rahimi

## Keywords:

Wavelet basis, Collocation method, Fractional integro-differential equation.

2000 MSC:
47G20, 45E05, 65L60.


#### Abstract

This paper describes and compares application of wavelet basis and Block-Pulse functions (BPFs) for solving fractional integrodifferential equation (FIDE) with a weakly singular kernel. First, a collocation method based on Haar wavelets (HW), Legendre wavelet (LW), Chebyshev wavelets (CHW), second kind Chebyshev wavelets (SKCHW), Cos and Sin wavelets (CASW) and BPFs are presented for driving approximate solution FIDEs with a weakly singular kernel. Error estimates of all proposed numerical methods are given to test the convergence and accuracy of the method. A comparative study of accuracy and computational time for the presented techniques is given.


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## 1. Introduction

Fractional calculus has been recently applied for modeling many physical phenomena in fields of nonlinear oscillation of earthquake, fluid-dynamic traffic, continuum and statistical mechanics, signal processing, control theory, and dynamics of interfaces between nanoparticles and subtracts [22, 2, 21, 20]. Consequently, considerable attentions has been given for deriving numerical solution of fractional functional equations. For example, Fourier transforms method, Laplace transforms method, fractional differential transform method, finite difference method, orthogonal functions, wavelets method, Adomian decomposition method, variational iteration method, and homotopy analysis method have been used for producing approximate solution of fractional functional equations[34, 32, 33, 31, 11, 9, 16].

Recently, different basis functions such as piecewise constant orthogonal functions, wavelets basis, orthogonal polynomials and Sine-Cosin functions have been used to estimate the solution of integral equations $[26,25 ?, 27,4,3,5,18,19,10,15,14]$. FIDEs with a weakly singular kernel are used in modelling different physical processes. For example, these kind of integro-differential equations are used in the heat conduction problem, radiative equilibrium, elasticity and fracture mechanics [26, 25, 27, 13]. In this paper, we describe application of BPFs and wavelets basis in solving the FIDEs with a weakly singular kernel. Consider the FIDE with weakly singular kernel

$$
\begin{equation*}
D_{*}^{\alpha} u(t)=f(t)+\int_{0}^{t} \frac{u(s) d s}{(t-s)^{\beta}}+\int_{0}^{1} k(s, t) u(s) d s \tag{1.1}
\end{equation*}
$$

with initial condition

$$
\begin{equation*}
u(0)=0, \tag{1.2}
\end{equation*}
$$

where $0<\alpha, \beta<1, a$ and $b$ are constants, $f(t)$ and $k(s, t)$ are known functions, $\mathrm{u}(\mathrm{t})$ is an unknown function and $D_{*}^{\alpha}$ denotes the fractional derivative defined by Caputo [22]. Operational matrices of fractional integration for BPFs and wavelets basis along with typical collocation method are used to obtain approximate solution of this FIDE with a weakly singular kernel. A comparison of the numerical results for different wavelets basis is presented.

The rest of this paper is organized as follows: In section 2 some preliminary definitions of fractional calculus are reviewed. Section 3 is devoted to the basic definitions of the BPFs and their properties. In section 4 we review definitions and properties of some commonly used wavelet basis in numerical solution of functional equations. A collocation method based on the wavelet and their operational matrix is proposed for solving fractional integro-differential equation with a weakly singular kernel is presented in Section 5. In Section 6 we introduce a process for estimating the error of approximate solution. A comparison of the numerical results is included in section 7. Finally, a conclusion is given in section 8.

## 2. Fractional calculus

Fractional order calculus is a branch of calculus which deal with integration and differentiation operators of non-integer order. Among the several formulations of the generalized derivative, the

Riemann-Liouville and Caputo definition are the most commonly used. In this section we give some necessary definitions and mathematical preliminaries of the fractional calculus which are required for establishing our results.
Definition 2.1. A real function $f(t), t>0$, is said to be in the space $C_{\mu}, \mu \in \mathbb{R}$ if there exists a real number $p>\mu$ and a function $f_{1}(t) \in C[0, \infty)$ such that $f(t)=t^{p} f_{1}(t)$, and it is said to be in the space $C_{\mu}^{n}, n \in \mathbb{N}$ if $f^{(n)} \in C_{\mu}$.
Definition 2.2. The Riemann-Liouville fractional integration of order $\alpha \geq 0$ of a function $f \in$ $C_{\mu}, \mu \geq-1$, is defined as

$$
\left(J^{\alpha} f\right)(t)= \begin{cases}\frac{1}{\Gamma(\alpha)} \int_{0}^{t}(t-\tau)^{\alpha-1} f(\tau) d \tau, & \alpha>0,  \tag{2.1}\\ f(t), & \alpha=0 .\end{cases}
$$

The Riemann-Liouville fractional operator $J^{\alpha}$ has the following properties:
(a) $J^{\alpha}\left(J^{\beta} f(t)\right)=J^{\beta}\left(J^{\alpha} f(t)\right)$,
(b) $J^{\alpha}\left(J^{\beta} f(t)\right)=J^{\alpha+\beta} f(t)$,
(c) $J^{\alpha} t^{\nu}=\frac{\Gamma(\nu+1)}{\Gamma(\alpha+\nu+1)} t^{\nu+\alpha}, \alpha, \beta \geq 0, \nu>-1$.

Definition 2.3. Riemann-Liouville fractional derivative of order $\alpha>0$ is defined as

$$
\begin{equation*}
D^{\alpha} f(t)=\frac{d^{n}}{d t^{n}} J^{n-\alpha} f(t), \quad n \in \mathbb{N}, \quad n-1<\alpha \leq n \tag{2.2}
\end{equation*}
$$

The Riemann-Liouville derivatives have certain disadvantages when trying to model real-world phenomena with fractional differential equations. Therefore, a modified fractional differential operator $D_{*}^{\alpha}$ was proposed by Caputo [22].
Definition 2.4. The fractional derivative of order $\alpha>0$ in the Caputo sense is defined as

$$
D_{*}^{\alpha} f(t)= \begin{cases}\frac{d^{n} f(t)}{d t^{n}}, & \alpha=n \in \mathbb{N},  \tag{2.3}\\ \frac{1}{\Gamma(n-\alpha)} \int_{0}^{t} \frac{f^{(n)}(\tau)}{(t-\tau)^{-\alpha n+1}} d \tau, t>0, & 0 \leq n-1<\alpha<n\end{cases}
$$

where $n$ is an integer, $t>0$, and $f \in C_{1}^{n}$.
Some useful relation between the Riemann-Liouvill and Caputo fractional operators is given by the following expression:
(a) $J^{\alpha} D_{*}^{\alpha} f(t)=f(t)-\sum_{k=0}^{n-1} f^{(k)}\left(0^{+}\right) \frac{t^{k}}{k!}, \quad n-1<\alpha \leq n, \quad t>0$.
(b) $D_{*}^{\alpha} J^{\alpha} f(t)=f(t)$.
(c) $J^{\alpha} t^{\beta}=\frac{\Gamma(\beta+1)}{\Gamma(\beta-\alpha+1)} t^{\beta-\alpha}$.
(d) $D_{*}^{\alpha} t^{\beta}= \begin{cases}\frac{\Gamma(\beta+1)}{\Gamma(\beta-\alpha+1)} t^{\beta-\alpha} & \beta \geq \alpha, \\ 0 & \beta<\alpha .\end{cases}$

For more details about fractional calculus please see [22].

## 3. Block pulse functions (BPFs)

BPFs have been studied by many authors and also have been applied for solving different problems. Here, we present a brief review of BPFs and its properties $[9,11]$.

The $m$-set of BPFs are defined as

$$
b_{i}(t)=\left\{\begin{array}{cc}
1 & (i-1) h \leq t<i h  \tag{3.1}\\
0 & \text { otherwise }
\end{array}\right.
$$

in which $t \in[0, T), i=1,2, \ldots, m$ and $h=\frac{T}{m}$. The BPFs set are disjoint with each other in the interval $[0, T)$ and

$$
\begin{equation*}
b_{i}(t) b_{j}(t)=\delta_{i j} b_{i}(t), \quad i, j=1,2, \ldots, m \tag{3.2}
\end{equation*}
$$

where $\delta_{i j}$ is the Kronecker delta. The set of BPFs defined in the interval [ $0, T$ ) are orthogonal with each other, that is

$$
\begin{equation*}
\int_{0}^{T} b_{i}(t) b_{j}(t) d t=h \delta_{i j}, \quad i, j=1,2, \ldots, m \tag{3.3}
\end{equation*}
$$

As $m$ tends to infinity, the $m$-set BPFs becomes a complete basis for $L^{2}[0, T)$, so that an arbitrary real bounded function $f(t)$, which is square integrable in the interval $[0, T)$, can be expanded into a BPFs series as

$$
\begin{equation*}
\int_{0}^{T} f^{2}(t) d t=\sum_{i=1}^{\infty} f_{i}^{2}\left\|b_{i}(t)\right\|^{2} \tag{3.4}
\end{equation*}
$$

where

$$
\begin{equation*}
f_{i}=\frac{1}{h} \int_{0}^{T} b_{i}(t) f(t) d t \tag{3.5}
\end{equation*}
$$

Any absolutely integrable function $f(t)$ defined over $[0, T)$ can be approximated by using BPFs as

$$
\begin{equation*}
f(t) \simeq f_{m}(t)=\sum_{i=1}^{m} f_{i} b_{i}(t)=F^{T} B(t) \tag{3.6}
\end{equation*}
$$

in which $f_{i}$ is obtained in (3.5), $B(t)$ and $F$ are $m$-vectors given by

$$
\begin{align*}
B(t) & =\left[b_{1}(t), \ldots, b_{m}(t)\right]^{T},  \tag{3.7}\\
F & =\left[f_{1}, f_{2}, \ldots ., f_{m}\right]^{T} . \tag{3.8}
\end{align*}
$$

Also the BPFs coefficients $f_{i}$ are obtained as (3.5), such that the mean square error between $f(t)$ and its BPFs expansion (3.6) in the interval of $t \in[0, T)$ is minimal. Morever, any two dimensional function $k(s, t) \in L^{2}([0, T] \times[0, T])$ can be expanded with respect to BPFs such as

$$
k(s, t) \simeq B(t)^{T} \Pi B(t)
$$

where $B(t)$ is the $m$-dimensional BPFs vectors respectively, and $\Pi$ is the $m \times m$ BPFs coefficient matrix with $(i, j)$-th element

$$
\Pi_{i j}=\frac{1}{h^{2}} \int_{0}^{T} \int_{0}^{T} k(s, t) b_{i}(t) b_{j}(s) d t d s, \quad i, j=1,2, \ldots, m
$$

and $h=\frac{T}{m}$.

### 3.1. BPFs operational matrices

Kilicman and Al Zhour [12] investigated the generalized integral operational matrix and showed that the integral of the matrix $B(t)$ defined in (3.7), can be approximated by

$$
\begin{equation*}
\int_{0}^{t} B(\tau) d \tau \simeq P B(t) \tag{3.9}
\end{equation*}
$$

where $P$ is the $m \times m$ operational matrix of one-time integral of $B(t)$. Moreover, we can compute the generalized operational matrices $P^{n}$ of $n$-times integration of $B(t)$ as:

$$
\begin{equation*}
\underbrace{\int_{0}^{t} \cdots \int_{0}^{t} B(\tau)(d \tau)^{n} \simeq P^{n} B(t) . ~ . ~ . ~}_{n \text {-times }} \tag{3.10}
\end{equation*}
$$

In [12] it is shown that $P^{n}$ has the following form:

$$
P^{n}=\frac{h^{n}}{(n+1)!}\left(\begin{array}{ccccc}
1 & \xi_{1} & \xi_{2} & \ldots & \xi_{m-1}  \tag{3.11}\\
0 & 1 & \xi_{1} & \ldots & \xi_{m-2} \\
0 & 0 & 1 & \ldots & \xi_{m-3} \\
0 & 0 & 0 & \ddots & \vdots \\
0 & 0 & 0 & 0 & 1
\end{array}\right)
$$

where $\xi_{i}=(i+1)^{n+1}-2 i^{n+1}+(i-1)^{n+1}$. As a generalization of the operational matrix $P$, the BPFs operational matrix of fractional integration is defined as

$$
\begin{equation*}
J^{\alpha} B(t)=P^{\alpha} B(t), \tag{3.12}
\end{equation*}
$$

where $P^{\alpha}$ is the $m \times m$ operational matrix of fractional integration and

$$
P^{\alpha}=\frac{h^{\alpha}}{\Gamma(\alpha+2)}\left(\begin{array}{ccccc}
1 & \xi_{1} & \xi_{2} & \ldots & \xi_{m-1}  \tag{3.13}\\
0 & 1 & \xi_{1} & \ldots & \xi_{m-2} \\
0 & 0 & 1 & \ldots & \xi_{m-3} \\
0 & 0 & 0 & \ddots & \vdots \\
0 & 0 & 0 & 0 & 1
\end{array}\right) \text {, }
$$

and $\xi_{i}=(i+1)^{\alpha+1}-2 i^{\alpha+1}+(i-1)^{\alpha+1}$. A detailed procedure for computing the operational matrix $P^{\alpha}$ can be found in [12].

## 4. Multiresolution analysis and wavelets

A multiresolution analysis (MRA) of $L^{2}(\mathbb{R})$ is defined as a sequence of closed subspaces $V_{j}$ of $L^{2}(\mathbb{R}), j \in \mathbb{Z}$, with the following properties $[7,8]$ :
(1) $V_{j} \subset V_{j+1}$,
(2) $v(x) \in V_{j} \Longleftrightarrow v(2 x) \in V_{j+1}$,
(3) $v(x) \in V_{0} \Longleftrightarrow v(x+1) \in V_{0}$,
(4) $\bigcup_{j=-\infty}^{\infty} V_{j}$ is dense in $L^{2}(\mathbb{R})$ and $\bigcap_{j=-\infty}^{\infty} V_{j}=0$,
(5) There exists a scaling function $\varphi(x) \in V_{0}$, such that the set $\{\varphi(x-k), k \in \mathbb{Z}\}$ forms a Riesz basis of $V_{0}$.
The function $\varphi(x)$ whose existence is asserted in (5) is called a scaling function of the given MRA. Moreover, a Riesz basis for a separable Hilbert space $H$ is a basis $\left\{g_{n}\right\}$ that is close to being orthogonal. That is, there exists a bounded invertible operator which maps $\left\{g_{n}\right\}$ onto an orthonormal basis. Any function $f \in L^{2}(\mathbb{R})$ can be projected onto the space $V_{n}$ by means of a projection operator $P_{n} f(t)$, as follows:

$$
\begin{equation*}
P_{n} f(t)=\sum_{k} a_{j, k} \varphi\left(2^{j} t-k\right) . \tag{4.1}
\end{equation*}
$$

A set of orthonormal wavelets can be constructed by using an MRA. Let $W_{0}$ be the orthogonal complement of $V_{0}$ in $V_{1}$; that is, $V_{1}=V_{0} \oplus W_{0}$. Then, if we dilate the elements of $W_{0}$ by $2^{j}$ we obtain a closed subspace $V_{j}$ in $V_{j+1}$ such that

$$
\begin{equation*}
V_{j+1}=V_{j} \oplus W_{j} \tag{4.2}
\end{equation*}
$$

Since $V_{j} \rightarrow 0$ as $j \rightarrow-\infty$ and $V_{j} \rightarrow L^{2}(\mathbb{R})$ as $j \rightarrow \infty$, we have

$$
\begin{equation*}
V_{j+1}=V_{j} \oplus W_{j}=\bigoplus_{r=-\infty}^{j} W_{r}, \tag{4.3}
\end{equation*}
$$

and

$$
\begin{equation*}
L^{2}(\mathbb{R})=\bigoplus_{j=-\infty}^{\infty} W_{j} \tag{4.4}
\end{equation*}
$$

Therefore, to find an orthonormal wavelets basis, we need to find a function $\psi$ in $W_{0}$ such that $\{\psi(t-k), k \in \mathbb{Z}\}$ is an orthonormal basis for $W_{0}$. In this case, the set $\left\{2^{\frac{j}{2}} \psi\left(2^{j} t-k\right), k \in \mathbb{Z}\right\}$ is an orthonormal basis for $W_{j}$. Consequently, the set $\left\{\psi_{j, k}(t)=2^{\frac{j}{2}} \psi\left(2^{j} t-k\right), j, k \in \mathbb{Z}\right\}$ is an orthonormal wavelet basis for $L^{2}(\mathbb{R})$. The function $\psi$ is called wavelet or mother wavelet function. More details about the concept MRA can be find in references [7, 8].

Wavelets basis constitute a family of functions constructed from dilation and translation of the mother wavelet $\psi$. When the dilation parameter $j$ and the translation parameter $k$ vary, we have the following family of wavelets

$$
\begin{equation*}
\psi_{j, k}(t)=2^{\frac{1}{2}} \psi\left(2^{j} t-k\right), j, k \in \mathbb{Z} \tag{4.5}
\end{equation*}
$$

As a powerful tool, wavelets have been extensively used in signal processing, numerical analysis, and many other areas. Wavelets permit accurate representation of a variety of functions and operators. Moreover, wavelet basis have been succesfully used to solve different kind of differential and integral equations [ $6,17,23,1,28,30,24]$. In this section we review basic definitions and properties of some commonly used wavelets basis in the field of numerical analysis and computational mathematics.

### 4.1. Haar wavelets

The orthogonal set of Haar wavelets $h_{n}(t)$ constitute a set of square waves defined as follows [25]

$$
\begin{equation*}
h_{n}(t)=2^{\frac{j}{2}} \psi\left(2^{j} t-k\right), \quad j \geq 0, \quad 0 \leq k<2^{j}, \quad n=2^{j}+k, \quad n, j, k \in \mathbb{N}, \tag{4.6}
\end{equation*}
$$

where

$$
h_{0}(t)=1, \quad 0 \leq t<1, \quad \psi(t)= \begin{cases}1, & 0 \leq t<\frac{1}{2}  \tag{4.7}\\ -1, & \frac{1}{2} \leq t<1\end{cases}
$$

Each Haar wavelet $h_{n}(t)$ has the support $\left[\frac{k}{2^{j}}, \frac{k+1}{2^{j}}\right)$, so that it is zero elsewhere in the interval $[0,1)$. Haar wavelets $h_{n}(t)$ are pairwise orthonormal in the interval $[0,1)$ and

$$
\begin{equation*}
\int_{0}^{1} h_{i}(t) h_{j}(t) d t=\delta_{i j} \tag{4.8}
\end{equation*}
$$

where $\delta_{i j}$ is the Kronecker delta. Any square integrable function $f(t)$ in the interval $[0,1)$ can be expanded in terms of Haar wavelets as

$$
\begin{equation*}
f(t)=c_{0} h_{0}(t)+\sum_{i=1}^{\infty} c_{i} h_{i}(t) \tag{4.9}
\end{equation*}
$$

where $c_{i}$ is given by

$$
\begin{equation*}
c_{i}=\int_{0}^{1} f(t) h_{i}(t) d t, \tag{4.10}
\end{equation*}
$$

The infinite series in Eq. (4.9) can be truncated after $\hat{m}$ terms, that is

$$
\begin{equation*}
f(t) \simeq c_{0} h_{0}(t)+\sum_{i=1}^{\hat{m}-1} c_{i} h_{i}(t), \quad i=2^{j}+k, \quad 0 \leq k<2^{j}, \tag{4.11}
\end{equation*}
$$

rewriting this equation in the vector form we have,

$$
\begin{equation*}
f(t) \simeq C^{T} \Psi(t)=\Psi(t)^{T} C \tag{4.12}
\end{equation*}
$$

in which $C$ and $H(t)$ are Haar coefficients and wavelets vectors as

$$
\begin{equation*}
C=\left[c_{0}, c_{1}, \ldots, c_{\hat{m}-1}\right]^{T} \tag{4.13}
\end{equation*}
$$

$$
\begin{equation*}
\Psi(t)=\left[h_{0}(t), h_{1}(t), \ldots, h_{\hat{m}-1}(t)\right]^{T} . \tag{4.14}
\end{equation*}
$$

Any two dimensional function $k(s, t) \in L^{2}[0,1) \times L^{2}[0,1)$ can be expanded with respect to Haar wavelets as

$$
\begin{equation*}
k(s, t)=\Psi^{T}(t) K \Psi(t), \tag{4.15}
\end{equation*}
$$

where $H(t)$ is the Haar wavelets vector and $K$ is the $\hat{m} \times \hat{m}$ Haar wavelets coefficients matrix with ( $i, l$ )-th element can be obtained as

$$
\begin{equation*}
k_{i j}=\int_{0}^{1} \int_{0}^{1} k(s, t) \Psi_{i}(t) \Psi_{j}(s) d t d s, \quad i, j=1,2, \ldots, \hat{m} . \tag{4.16}
\end{equation*}
$$

### 4.2. Legendre wavelets

Legendre wavelets $\psi_{m n}(t)$ are defined on the interval $[0,1)$ as $[18,19,10]$

$$
\psi_{m n}(t)=\left\{\begin{array}{cl}
\sqrt{m+\frac{1}{2}} 2^{\frac{k+1}{2}} P_{m}\left(2^{k+1} t-(2 n+1)\right) & \frac{n}{2^{k}} \leq t<\frac{n+1}{2^{k}}  \tag{4.17}\\
0 & \text { otherwise },
\end{array}\right.
$$

where $n=0,1, \ldots, 2^{k}-1$ and $m=0,1, \cdots, M-1$ is the degree of the Legendre polynomials for a fixed positive integer $M$. Here $P_{m}(t)$ are the well-known Legendre polynomials of degree $m$. The Legendre wavelets $\left\{\psi_{n m}(x) \mid n=0,1, \ldots, 2^{k}-1, m=0,1,2, \ldots, M-1\right\}$ forms an orthonormal basis for $L^{2}[0,1]$ with respect to the weight function $w(t)=1$.

Any square integrable function $f(x)$ defined over $[0,1)$ can be expanded in terms of the extended Legendre wavelets as

$$
\begin{equation*}
f(t) \simeq \sum_{n=0}^{\infty} \sum_{m=0}^{\infty} c_{n m} \psi_{n m}(x) \tag{4.18}
\end{equation*}
$$

where $c_{m n}=\left(f(t), \psi_{m n}(t)\right)$ and (.,.) denotes the inner product on $L^{2}[0,1]$. If the infinite series in (4.18) is truncated, then it can be written as

$$
\begin{equation*}
f(t) \simeq \sum_{n=0}^{2^{k}-1} \sum_{m=0}^{M-1} c_{m n} \psi_{m n}(x)=C^{T} \Psi(t), \tag{4.19}
\end{equation*}
$$

where $C$ and $\Psi(t)$ are $\hat{m}=2^{k} M$ column vectors given by

$$
\begin{gather*}
C=\left[c_{00}, \ldots, c_{0(M-1)}\left|c_{10}, \ldots, c_{1(M-1)}, \ldots,\right| c_{\left(2^{k}-1\right) 0}, \ldots, c_{\left(2^{k}-1\right)(M-1)}\right]^{T}  \tag{4.20}\\
\Psi(t)=\left[\psi_{00}(t), \ldots, \psi_{0(M-1)}(t)\left|\psi_{10}(t), \ldots, \psi_{1(M-1)}(t)\right|, \ldots, \mid \psi_{\left(2^{k}-1\right) 0}(t), \ldots, \psi_{\left(2^{k}-1\right)(M-1)}(t)\right]^{T} .
\end{gather*}
$$

By changing indices in the vectors $\Psi(x)$ and $C$ the series (4.20) can be rewritten as

$$
\begin{equation*}
f(t) \simeq \sum_{i=1}^{\hat{m}} c_{i} \psi_{i}(t)=C^{T} \Psi(t) \tag{4.21}
\end{equation*}
$$

where

$$
\begin{equation*}
C=\left[c_{1}, c_{2}, \ldots, c_{\hat{m}}\right], \quad \Psi(t)=\left[\psi_{1}(t), \psi_{2}(t), \ldots, \psi_{\hat{m}}(t)\right], \tag{4.22}
\end{equation*}
$$

and

$$
\begin{equation*}
c_{i}=c_{n m}, \quad \psi_{i}(x)=\psi_{n m}(x), \quad i=n M+m+1 \tag{4.23}
\end{equation*}
$$

Similarly, any two dimensional function $k(s, t) \in L^{2}([0,1] \times[0,1])$ can be expanded into Legendre wavelets basis as

$$
\begin{equation*}
k(s, t) \approx \sum_{i=1}^{\hat{m}} \sum_{j=1}^{\hat{m}} k_{i j} \psi_{i}(s) \psi_{j}(t)=\Psi^{T}(s) K \Psi(t), \tag{4.24}
\end{equation*}
$$

where $K=\left[k_{i j}\right]$ and $k_{i j}=\left(\psi_{i}(s),\left(u(s, t), \psi_{j}(t)\right)\right)$.

### 4.3. Chebyshev wavelets

Chebyshev wavelets $\psi_{n m}(x)$ are defined on the interval $[0,1)$ by [ $\left.9,15,14\right]$

$$
\psi_{n m}(t)=\left\{\begin{array}{cc}
2^{\frac{k+1}{2}} \tilde{T}_{m}\left(2^{k} t-(2 n+1)\right), & \frac{n}{2^{k}} \leq x \leq \frac{n+1}{2^{k}}  \tag{4.25}\\
0, & \text { otherwise }
\end{array},\right.
$$

where

$$
\tilde{T}_{m}(t)=\left\{\begin{array}{ll}
\frac{1}{\sqrt{\pi}}, & m=0 \\
\sqrt{\frac{2}{\pi}} T_{m}(t), & m>0
\end{array},\right.
$$

and $T_{m}(t)$ are the well-known Chebyshev polynomials of degree $m$. Chebyshev wavelets $\left\{\psi_{n m}(x) \mid n=\right.$ $\left.0,1, \ldots, 2^{k}-1, m=0,1,2, \ldots, M-1\right\}$ form an orthonormal basis for $L_{w_{n}}^{2}[0,1]$ with respect to the weight function $w_{n}(t)=w\left(2^{k+1} t-(2 n+1)\right)$, in which $w(t)=\frac{1}{\sqrt{1-t^{2}}}$.

By using the orthonormality of the Chebyshev wavelets, any function $f(t)$ over $[0,1)$; squareintegrable with respect to the measure $\mathbf{w}(t) d t$; with $\mathbf{w}(t)=w_{n k}(t)$; for $\frac{n}{2^{k}} \leq t \leq \frac{n+1}{2^{k}}$; and $w_{n k}(t)=$ $w\left(2^{k+1} t-2 n+1\right)$; being $w(t)=\frac{1}{\sqrt{1-t^{2}}}$ can be expanded in terms of the Chebyshev wavelets as

$$
\begin{equation*}
f(t) \simeq \sum_{n=0}^{\infty} \sum_{m=0}^{\infty} c_{n m} \psi_{n m}(t) \tag{4.26}
\end{equation*}
$$

where $c_{m n}=\left(f(t), \psi_{m n}(t)\right)_{w_{n k}}$ and $(., .)_{w_{n k}}$ denotes the inner product on $L_{w_{n k}}^{2}[0,1]$. If the infinite series in (4.26) is truncated, then it can be written as

$$
\begin{equation*}
f(t) \simeq \sum_{n=0}^{2^{k}-1} \sum_{m=0}^{M-1} c_{m n} \psi_{m n}(x)=C^{T} \Psi(t) \tag{4.27}
\end{equation*}
$$

where $C$ and $\Psi(t)$ are $\hat{m}=2^{k} M$ column vectors given by

$$
C=\left[c_{00}, \ldots, c_{0(M-1)}\left|c_{10}, \ldots, c_{1(M-1)}\right|, \ldots, \mid c_{\left(2^{k}-1\right) 0}, \ldots, c_{\left(2^{k}-1\right)(M-1)}\right]^{T}
$$

$$
\begin{equation*}
\Psi(x)=\left[\psi_{00}(t), \ldots, \psi_{0(M-1)}(t)\left|\psi_{10}(t), \ldots, \psi_{1(M-1)}(t)\right|, \ldots, \mid \psi_{\left(2^{k}-1\right) 0}(t), \ldots, \psi_{\left(2^{k}-1\right)(M-1)}(t)\right]^{T} \tag{4.28}
\end{equation*}
$$

By changing indices in the vectors $\Psi(t)$ and $C$ the series (4.28) can be rewritten as

$$
\begin{equation*}
f(t) \simeq \sum_{i=1}^{\hat{m}} c_{i} \psi_{i}(t)=C^{T} \Psi(t) \tag{4.29}
\end{equation*}
$$

where

$$
\begin{equation*}
C=\left[c_{1}, c_{2}, \ldots, c_{\hat{m}}\right], \quad \Psi(x)=\left[\psi_{1}(x), \psi_{2}(x), \ldots, \psi_{\hat{m}}(x)\right], \tag{4.30}
\end{equation*}
$$

and

$$
c_{i}=c_{n m}, \quad \psi_{i}(t)=\psi_{n m}(t), \quad i=n M+m+1 .
$$

Similarly, any two dimensional function $k(s, t) \in L_{\mathbf{w}}^{2} \otimes \mathbf{w}([0,1] \times[0,1])$ can be expanded into Chebyshev wavelets basis as

$$
\begin{equation*}
k(s, t) \approx \sum_{i=1}^{\hat{m}} \sum_{j=1}^{\hat{m}} k_{i j} \psi_{i}(s) \psi_{j}(t)=\Psi^{T}(s) K \Psi(t) \tag{4.31}
\end{equation*}
$$

where $K=\left[k_{i j}\right]$ is an $\hat{m} \times \hat{m}$ matrix and $k_{i j}=\left(\psi_{i}(s),\left(k(s, t), \psi_{j}(t)\right)_{w_{n k}}\right)_{w_{n k}}$.

### 4.4. Second kind Chebyshev wavelets

Second kind Chebyshev wavelets $\psi_{n m}(t)$ are defined on the interval [0,1) by [29]

$$
\psi_{n m}(t)=\left\{\begin{array}{cc}
\sqrt{\frac{2}{\pi}} 2^{\frac{k+1}{2}} U_{m}\left(2^{k+1} t-2 n-1\right), & \frac{n}{2^{k}} \leq x \leq \frac{n+1}{2^{k}}  \tag{4.32}\\
0, & \text { otherwise },
\end{array},\right.
$$

where $U_{m}(t)$ is the second kind Chebyshev polynomials of degree $m$, given by

$$
\begin{equation*}
U_{m}(t)=\frac{\sin ((m+1) \theta)}{\sin (\theta)}, \quad t=\cos (\theta) . \tag{4.33}
\end{equation*}
$$

The second kind Chebyshev wavelets $\left\{\psi_{n m}(t) \mid n=0,1, \ldots, 2^{k}-1, m=0,1,2, \ldots, M-1\right\}$ forms an orthonormal basis for $L_{w_{n k}}^{2}[0,1]$ with respect to the weight function $w_{n k}(t)=w\left(2^{k+1} t-2 n-1\right)$, in which $w(t)=\sqrt{1-t^{2}}$. By using the orthonormality of the second kind Chebyshev wavelets, any square integrable function $f(t)$ defined over $[0,1)$ can be expanded in terms of the second kind Chebyshev wavelets as

$$
\begin{equation*}
f(t) \simeq \sum_{n=0}^{\infty} \sum_{m=0}^{\infty} c_{n m} \psi_{n m}(t) \tag{4.34}
\end{equation*}
$$

where $c_{m n}=\left(f(t), \psi_{m n}(t)\right)_{w_{n k}}$ and $(., .)_{w_{n k}}$ denotes the inner product on $L_{w_{n k}}^{2}[0,1]$. If the infinite series in (4.42) is truncated, then it can be written as

$$
\begin{equation*}
f(t) \simeq \sum_{n=0}^{2^{k}-1} \sum_{m=0}^{M-1} c_{m n} \psi_{m n}(x)=C^{T} \Psi(t) \tag{4.35}
\end{equation*}
$$

where $C$ and $\Psi(t)$ are $\hat{m}=2^{k} M$ column vectors given by

$$
\begin{gather*}
C=\left[c_{00}, \ldots, c_{0(M-1)}\left|c_{10}, \ldots, c_{1(M-1)}\right|, \ldots, \mid c_{\left(2^{k}-1\right) 0}, \ldots, c_{\left(2^{k}-1\right)(M-1)}\right]^{T} \\
\Psi(x)=\left[\psi_{00}(t), \ldots, \psi_{0(M-1)}(t)\left|\psi_{10}(t), \ldots, \psi_{1(M-1)}(t)\right|, \ldots, \mid \psi_{\left(2^{k}-1\right) 0}(t), \ldots, \psi_{\left(2^{k}-1\right)(M-1)}(t)\right]^{T} . \tag{4.36}
\end{gather*}
$$

By changing indices in the vectors $\Psi(t)$ and $C$ the series (4.36) can be rewritten as

$$
\begin{equation*}
f(t) \simeq \sum_{i=1}^{\hat{m}} c_{i} \psi_{i}(t)=C^{T} \Psi(t) \tag{4.37}
\end{equation*}
$$

where

$$
\begin{equation*}
C=\left[c_{1}, c_{2}, \ldots, c_{\hat{m}}\right], \quad \Psi(x)=\left[\psi_{1}(x), \psi_{2}(x), \ldots, \psi_{\hat{m}}(x)\right], \tag{4.38}
\end{equation*}
$$

and

$$
\begin{equation*}
c_{i}=c_{n m}, \quad \psi_{i}(t)=\psi_{n m}(t), \quad i=n M+m+1 . \tag{4.39}
\end{equation*}
$$

Similarly, any two dimensional function $k(s, t) \in L^{2}([0,1] \times[0,1])$ can be expanded into second kind Chebyshev wavelets basis as

$$
\begin{equation*}
k(s, t) \approx \sum_{i=1}^{\hat{m}} \sum_{j=1}^{\hat{m}} k_{i j} \psi_{i}(s) \psi_{j}(t)=\Psi^{T}(s) K \Psi(t), \tag{4.40}
\end{equation*}
$$

where $K=\left[k_{i j}\right]$ and $k_{i j}=\left(\psi_{i}(s),\left(u(s, t), \psi_{j}(t)\right)_{w_{n k}}\right)_{w_{n k k}}$.

### 4.5. CAS Wavelet

CAS wavelets $\psi_{n m}(t)$ are defined on the interval $[0,1)$ as follows [26]

$$
\psi_{m n}(t)= \begin{cases}2^{\frac{k}{2}} C A S_{m}\left(2^{k} t-n+1\right), & \frac{n-1}{2^{k}} \leq t<\frac{n-1}{2^{k}}  \tag{4.41}\\ 0, & \text { otherwise }\end{cases}
$$

where $C A S_{m}(t)=\cos (2 m \pi t)+\sin (2 m \pi t)$. The set of CAS wavelets $\left\{\psi_{n m}(t) \mid n=0,1, \ldots, 2^{k}-1, m=\right.$ $-M, \ldots 0,1,2, \ldots, M-1\}$ forms an orthonormal basis for $L^{2}([0,1))$. This implies that any square inegrable function $f(t)$ defined over $[0,1)$ can be expanded in terms of the CAS wavelets as

$$
\begin{equation*}
f(t) \simeq \sum_{n=0}^{\infty} \sum_{m \in \mathbb{Z}}^{\infty} c_{n m} \psi_{n m}(t) \tag{4.42}
\end{equation*}
$$

where $c_{m n}=\left(f(t), \psi_{m n}(t)\right)$ and (.,.) is the inner product on $L^{2}[0,1]$. If the infinite series in (4.42) is truncated, then it can be written as

$$
\begin{equation*}
f(t) \simeq \sum_{n=0}^{2^{k}-1} \sum_{m=-M}^{M} c_{m n} \psi_{m n}(x)=C^{T} \Psi(t) \tag{4.43}
\end{equation*}
$$

where $C$ and $\Psi(t)$ are $\hat{m}=2^{k}(2 M+1)$ column vectors given by

$$
\begin{align*}
C & =\left[c_{0,-M}, \ldots, c_{0, M}, \ldots, c_{1,-M}, \ldots, c_{1, M}, \ldots, c_{\left(2^{k}-1\right),-M}, \ldots, c_{\left(2^{k}-1\right), M}\right]^{T}, \\
\Psi(t) & =\left[\psi_{0,-M}, \ldots, \psi_{0, M}, \ldots, \psi_{1,-M}, \ldots, \psi_{1, M}, \ldots, \psi_{\left(2^{k}-1\right),-M}, \ldots, \psi_{\left(2^{k}-1\right), M}\right]^{T}, \tag{4.44}
\end{align*}
$$

By changing indices in the vectors $\Psi(t)$ and $C$ the series (4.44) can be rewritten as

$$
\begin{equation*}
f(t) \simeq \sum_{i=1}^{\hat{m}} c_{i} \psi_{i}(t)=C^{T} \Psi(t) \tag{4.45}
\end{equation*}
$$

where

$$
\begin{equation*}
C=\left[c_{1}, c_{2}, \ldots, c_{\hat{m}}\right], \quad \Psi(x)=\left[\psi_{1}(x), \psi_{2}(x), \ldots, \psi_{\hat{m}}(x)\right], \tag{4.46}
\end{equation*}
$$

and

$$
\begin{equation*}
c_{i}=c_{n m}, \quad \psi_{i}(t)=\psi_{n m}(t), \quad i=(n-1)(2 M+1)+M+m+1 . \tag{4.47}
\end{equation*}
$$

Moreover, any two dimensional function $k(s, t) \in L^{2}([0,1] \times[0,1])$ can be expanded into second kind Chebyshev wavelets basis as

$$
\begin{equation*}
k(s, t) \approx \sum_{i=1}^{\hat{m}} \sum_{j=1}^{\hat{m}} k_{i j} \psi_{i}(s) \psi_{j}(t)=\Psi^{T}(s) K \Psi(t) \tag{4.48}
\end{equation*}
$$

where $K=\left[k_{i j}\right]$ and $k_{i j}=\left(\psi_{i}(s),\left(u(s, t), \psi_{j}(t)\right)_{w_{n k}}\right)_{w_{n k}}$.

## 5. Operational matrix of the fractional integration

The wavelets basis $\Psi(t)$ can be expressed in the $\hat{m}$-dimensional BPFs. Next theorem describe the relation between the wavelet basis $\Psi(t)$ and BPFs $B(t)$.
Theorem 5.1. Let $\Psi(t)$ and $B(t)$ be the $\hat{m}$-dimensional wavelets and BPFs vector respectively, the vector $\Psi(t)$ can be expanded by BPFs vector $B(t)$ as

$$
\begin{equation*}
\Psi(t) \simeq Q B(t) \tag{5.1}
\end{equation*}
$$

where $Q$ is an $\hat{m} \times \hat{m}$ block matrix and

$$
\begin{equation*}
Q_{i j}=\psi_{i}\left(\frac{2 j-1}{2 \hat{m}}\right), \quad i, j=1,2, \ldots, \hat{m} \tag{5.2}
\end{equation*}
$$

$\operatorname{Proof.}$ Let $\psi_{i}(t), i=1,2, \ldots, \hat{m}$ be the $i$-th element of the wavelets vector $\psi(t)$. Expanding $\psi_{i}(t)$ into an $\hat{m}$-term vector of BPFs, we have

$$
\begin{equation*}
\psi_{i}(t) \simeq \sum_{k=1}^{\hat{m}} Q_{i k} b_{k}(t), \quad i=1,2, \ldots, \hat{m}, \tag{5.3}
\end{equation*}
$$

taking the collocation points $\eta_{j}=\frac{2 j-1}{2 \tilde{m}}$ and evaluating relation (5.3) we get

$$
\begin{equation*}
\psi_{i}\left(\eta_{j}\right) \simeq \sum_{k=1}^{\hat{m}} Q_{i k} b_{k}\left(\eta_{j}\right)=Q_{i j}, \quad i, j=1,2, \ldots, \hat{m}, \tag{5.4}
\end{equation*}
$$

and this prove the desired result.
Now we derive the operational matrices of integration for the wavelets vector $\Psi(t)$. A general procedures for forming these matrix will be described in next theorem. First, we remind some useful results for BPFs.

Lemma 5.2. [12] Let $B(t)$ be the $\hat{m}$-dimensional BPFs vector defined in (3.7), then integration of this vector can be derived as

$$
\begin{equation*}
\int_{0}^{t} B(s) d s \simeq P B(t) \tag{5.5}
\end{equation*}
$$

where $P$ is called the operational matrix of integration for BPFs and is given by

$$
P=\frac{h}{2}\left[\begin{array}{ccccc}
1 & 2 & 2 & \ldots & 2  \tag{5.6}\\
0 & 1 & 2 & \ldots & 2 \\
0 & 0 & 1 & \vdots & \vdots \\
\vdots & \vdots & \vdots & \ddots & 2 \\
0 & 0 & 0 & \ldots & 1
\end{array}\right]_{\hat{m} \times \hat{m}} .
$$

Lemma 5.3. [12] Let $B(t)$ be the $\hat{m}$-dimensional BPFs vector defined in (3.7), then integration of this vector can be derived as

$$
\begin{equation*}
J^{\alpha} B(t)=P^{\alpha} B(t), \tag{5.7}
\end{equation*}
$$

where $P^{\alpha}$ is called the operational matrix of integration for BPFs and is given by

$$
P^{\alpha}=\frac{h^{\alpha}}{\Gamma(\alpha+2)}\left[\begin{array}{ccccc}
1 & \xi_{1} & \xi_{2} & \ldots & \xi_{m-1}  \tag{5.8}\\
0 & 1 & \xi_{1} & \ldots & \xi_{m-2} \\
0 & 0 & 1 & \ldots & \xi_{m-3} \\
0 & 0 & 0 & \ddots & \vdots \\
0 & 0 & 0 & 0 & 1
\end{array}\right] .
$$

Theorem 5.4. Suppose $\Psi(t)$ be an $\hat{m}$-dimensional wavelets vector, the integral of this vector can be derived as

$$
\begin{equation*}
\int_{0}^{t} \Psi(s) d s \simeq Q P Q^{-1} \Psi(t)=\Lambda \Psi(t) \tag{5.9}
\end{equation*}
$$

where $Q$ is introduced in (5.1) and $P$ is the operational matrix of integration for BPFs derived in (5.6).

Proof. Let $\Psi(t)$ be the wavelets vector, by using Theorem 5.1 and Lemma 5.3 we have

$$
\begin{equation*}
\int_{0}^{t} \Psi(s) d s \simeq \int_{0}^{t} Q B(s) d s=Q \int_{0}^{t} B(s) d s=Q P B(t) \tag{5.10}
\end{equation*}
$$

now theorem 5.1 results

$$
\begin{equation*}
\int_{0}^{t} \Psi(s) d s \simeq Q P B(t)=Q P Q^{-1} \Psi(t)=\Lambda \Psi(t) \tag{5.11}
\end{equation*}
$$

by using this identity we obtain the desired result.
Theorem 5.5. Let $\Psi(t)$ be the an $\hat{m}$-dimensional wavelets vector, the operational matrix of the fractional order integration for $\Psi(t)$ can be derived as

$$
\begin{equation*}
J^{\alpha} \Psi(t)=Q P^{\alpha} Q^{-1} \Psi(t)=\Lambda^{\alpha} \Psi(t), \tag{5.12}
\end{equation*}
$$

where $\Lambda^{\alpha}$ is called the operational matrix of second kind Chebyshev wavelets, $Q$ is the matrix introduced in (5.1) and $P^{\alpha}$ is the operational matrix of fractional integration for BPFs derived in (5.8).

Proof. By using Theorem 5.1 we have

$$
\begin{equation*}
J^{\alpha} \Psi(t)=J^{\alpha} Q \Phi(t)=Q F^{\alpha} \Phi(t)=Q F^{\alpha} Q^{-1} \Psi(t)=P^{\alpha} \Psi(t), \tag{5.13}
\end{equation*}
$$

so, the second kind Chebyshev wavelet operational matrix of the fractional order integration $P^{\alpha}$ is given by

$$
\begin{equation*}
P^{\alpha}=Q F^{\alpha} Q^{-1} . \tag{5.14}
\end{equation*}
$$

and this completes the proof.

## 6. Method of solution

In this section, a collocation method based on BPFs and wavelet basis is presented for approximating solution of FIDE with a weakly singular kernel defined in (1.1). The presented technique can be applied by using BPFs and all wavelets basis introduced in the previous section. From now
on by $\Phi(t)$ we mean BPFs or any introduced wavelet basis vector. Consider FIDE with a weakly singular kernel (1.1), we first approximate functions $D_{*}^{\alpha} u(t)$ and $k(t, s)$ as

$$
\begin{equation*}
D_{*}^{\alpha} u(t)=C^{T} \Phi(t), \quad k(t, s)=\Phi(t)^{T} K \Phi(t) \tag{6.1}
\end{equation*}
$$

where $\Phi(t)$ can be BPFs or wavelet vector, $C$ is an unknown vector and $K$ is a known coefficient matrix of $k(t, s)$ corresponding to the basis vector $\Phi(t)$. By using the properties of Caputo fractional operators $D_{*}^{\alpha}$ and operational matrix of fractional oreder on the basis vector $\Phi(t)$ we get

$$
\begin{equation*}
u(t)=J^{\alpha}\left(D_{*}^{\alpha} u(t)\right)=C^{T} J^{\alpha} \Phi(t)=C^{T} P^{\alpha} \Phi(t), \tag{6.2}
\end{equation*}
$$

substituting Eqs. (6.1) and (6.2) into Eq. (1.1), we have

$$
\begin{align*}
C^{T} \Phi(t) & =F^{T} \Phi(t)+\int_{0}^{t} \frac{C^{T} P^{\alpha} \Phi(s) d s}{(t-s)^{\beta}}+\int_{0}^{1} \Phi(t)^{T} K \Phi(s) C^{T} P^{\alpha} \Phi(s) d s \\
& =F^{T} \Phi(t)+C^{T} P^{\alpha} \int_{0}^{t} \frac{\Phi(s) d s}{(t-s)^{\beta}}+\Phi(t)^{T} K\left(\int_{0}^{1} \Phi(s) \Phi(s)^{T} d s\right)\left(P^{\alpha}\right)^{T} C  \tag{6.3}\\
& =F^{T} \Phi(t)+C^{T} P^{\alpha} \int_{0}^{t} \frac{\Phi(s) d s}{(t-s)^{\beta}}+h \Phi(t)^{T} K Q\left(P^{\alpha} Q\right)^{T} C,
\end{align*}
$$

and for the case that $\Phi(t)$ is the BPFs vector, the matrix $Q=I_{\hat{m}}$ will be the identity matrix. Now we consider the weakly singular integral $\int_{0}^{t} \frac{\Phi(s) d s}{(t-s)^{\beta}}$. For $(i-1) h \leq t \leq i h$, this singular integral can be approximated as

$$
\begin{align*}
& \int_{0}^{t} \frac{\Phi(s) d s}{(t-s)^{\beta}}=Q \int_{0}^{t} \frac{B(s) d s}{(t-s)^{\beta}}=Q\left[\int_{0}^{h} \frac{d s}{(t-s)^{\beta}}, \int_{h}^{2 h} \frac{d s}{(t-s)^{\beta}} \cdots, \int_{(i-1) h}^{t} \frac{d s}{(t-s)^{\beta}}, 0, \ldots, 0\right]^{T} \\
& =Q\left[\frac{t^{-\beta+1}-(t-h)^{-\beta+1}}{\beta-1}, \frac{(t-h)^{-\beta+1}-(t-2 h)^{-\beta+1}}{\beta-1}, \ldots, \frac{(t-(i-1) h)^{-\beta+1}}{\beta-1}, 0, \ldots, 0\right]^{T}=V(t) . \tag{6.4}
\end{align*}
$$

Substituting the vector $V(t)$ in Eq. (6.3), we get

$$
\begin{equation*}
C^{T} \Phi(t)=F^{T} \Phi(t)+C^{T} P^{\alpha} V(t)+h \Phi(t)^{T} K Q\left(P^{\alpha} Q\right)^{T} C, \tag{6.5}
\end{equation*}
$$

by taking the appropriate collocation points $t_{i}, i=1, \ldots, \hat{m}$ and evaluating Eq. (6.5) we obtain the following linear system of algebraic equations for the unknown vector $C$

$$
\begin{equation*}
C^{T} \Phi\left(t_{i}\right)-F^{T} \Phi\left(t_{i}\right)-C^{T} P^{\alpha} V\left(t_{i}\right)-h \Phi\left(t_{i}\right)^{T} K Q\left(P^{\alpha} Q\right)^{T} C=0, \quad i=0,1, \ldots, m \tag{6.6}
\end{equation*}
$$

By solving this linear system and determining vector $C$, we can approximate solution of fractional integro-differential equation with a weakly singular kernel (1.1) by substituting the obtained vector $C$ in Eq. (6.2).

## 7. Estimation of the error function

Suppose $u(t)$ is the exact solution of (1.1) and $u_{\hat{m}}(t)$ is the approximate solution for $u(t)$. Here, we introduce a process for estimating the error of approximate solution, i. e. $e_{\hat{m}}(t)=u(t)-u_{\hat{m}}(t)$. First, by using definition of fractional integration operator $J^{\alpha}$, the solution of FIDE with a weakly singular kernel (1.1) can be written as
$u(s)=\frac{1}{\Gamma(\alpha)} \int_{0}^{t} \frac{f(\tau) d \tau}{(t-\tau)^{1-\alpha}}+\frac{1}{\Gamma(\alpha)} \int_{0}^{t} \frac{1}{(t-\tau)^{1-\alpha}} \int_{0}^{\tau} \frac{u(s) d s d \tau}{(\tau-s)^{\beta}}+\frac{1}{\Gamma(\alpha)} \int_{0}^{t} \int_{0}^{1} \frac{k(s, \tau) u(s)}{(t-\tau)^{1-\alpha}} d s d \tau(7.1)$
now consider the perturbation function $r_{\hat{m}}(t)$ that depends only on $u_{\hat{m}}(t)$ as

$$
\begin{align*}
r_{\hat{m}}(t)= & \frac{1}{\Gamma(\alpha)} \int_{0}^{t} \frac{f(\tau) d \tau}{(t-\tau)^{1-\alpha}}+\frac{1}{\Gamma(\alpha)} \int_{0}^{t} \frac{1}{(t-\tau)^{1-\alpha}} \int_{0}^{\tau} \frac{u_{\hat{m}}(s) d s d \tau}{(\tau-s)^{\beta}} \\
& +\frac{1}{\Gamma(\alpha)} \int_{0}^{t} \frac{1}{(t-\tau)^{1-\alpha}} \int_{0}^{1} k(s, \tau) u_{\hat{m}}(s) d s d \tau-u_{\hat{m}}(t), \tag{7.2}
\end{align*}
$$

subtracting (7.2) from (7.1) we obtain
$e_{\hat{m}}(t)=r_{\hat{m}}(t)+\frac{1}{\Gamma(\alpha)} \int_{0}^{t} \frac{1}{(t-\tau)^{1-\alpha}} \int_{0}^{\tau} \frac{e_{\hat{m}}(s) d s d \tau}{(\tau-s)^{\beta}}+\frac{1}{\Gamma(\alpha)} \int_{0}^{t} \frac{1}{(t-\tau)^{1-\alpha}} \int_{0}^{1} k(s, \tau) e_{\hat{m}}(s) d s d \tau$,
this is a fractional integral equations in which the error function $e_{\hat{m}}(t)$ is unknown. Obviously, we can apply the proposed collocation method as given in previous section for this system to find an approximation of the error function $e_{\hat{m}}(t)$.

## 8. Numerical results and discussion

In this section, we will present numerical experiments derived by using collocation method described in Section 6. The results of the proposed method for different kind of wavelet basis are also compared with exact solution. All computations are performed by Maple 17 with 20 digits precision and Intel Core 2 Duo CPU 2.50 GHz package.

Example 8.1. Let us consider the following FIDE with weakly singular kernel [13]

$$
D_{*}^{0.25} u(t)=f(t)+\frac{1}{2} \int_{0}^{t} \frac{u(s) d s}{(t-s)^{\frac{1}{2}}}+\frac{1}{3} \int_{0}^{1}(t-s) u(s)
$$

with the initial condition $u(0)=0$ and

$$
f(t)=\frac{\Gamma(3)}{\Gamma(2.75)} t^{1.75}+\frac{\Gamma(4)}{\Gamma(3.75)} t^{2.75}-\frac{\sqrt{\pi} \Gamma(3)}{2 \Gamma(3.5)} t^{2.5}-\frac{\sqrt{\pi} \Gamma(4)}{2 \Gamma(4.5)} t^{3.5}-\frac{7 t}{36}+\frac{3}{20} .
$$

The exact solution of this equation is $u(t)=t^{2}+t^{3}$. The presented collocation method in section 6 with wavelet and BPFs basis is used for approximating solution of this FIDE with weakly singular
kernel. Table 1 presents the maximum absolute error of the numerical results derived by different wavelet basis and BPFs for various values of $\hat{m}$. As numerical results in Table 1 reveal, the LW, CHW and SKCHW have same convergence behavior and they are more accurate in comparison with other wavelets basis and BPFs. Moreover, computational time of different wavelet and BPFs methods for $\hat{m}=64$ are listed in Table 2. From this Table it is possible to see that the computational time of CASW is higher than other kind of used basis function and BPFs has the minimum computational time.

Table 1: Comparison of the maximum absolute error for different wavelet basis and various values of $\hat{m}$.

|  | $\hat{m}=24$ | $\hat{m}=48$ | $\hat{m}=64$ |
| :---: | :---: | :---: | :---: |
| BPFs | $1.22 \times 10^{-1}$ | $5.14 \times 10^{-2}$ | $4.01 \times 10^{-2}$ |
| HW | $2.23 \times 10^{-1}$ | $4.32 \times 10^{-2}$ | $3.82 \times 10^{-2}$ |
| LW | $5.21 \times 10^{-3}$ | $1.20 \times 10^{-3}$ | $1.13 \times 10^{-3}$ |
| CHW | $4.86 \times 10^{-3}$ | $1.18 \times 10^{-3}$ | $1.12 \times 10^{-3}$ |
| SKCHW | $5.25 \times 10^{-3}$ | $1.42 \times 10^{-3}$ | $1.12 \times 10^{-3}$ |
| CASW | $2.53 \times 10^{-1}$ | $5.50 \times 10^{-2}$ | $1.52 \times 10^{-2}$ |

Table 2: Comparison of computational time (in seconds) for different wavelet basis and $\hat{m}=64$.

|  | BPFs | HW | LW | CHW | SKCHW | CASW |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| CPU time (sec) | 135.695 | 1380.141 | 140.436 | 148.217 | 142.176 | 187.042 |

Example 8.2. Consider the FIDE with weakly singular kernel [13]

$$
D_{*}^{0.15} u(t)=f(t)+\frac{1}{4} \int_{0}^{t} \frac{u(s) d s}{(t-s)^{\frac{1}{2}}}+\frac{1}{7} \int_{0}^{1} e^{t+s} u(s)
$$

in which $u(0)=0$ and

$$
f(t)=\frac{\Gamma(3)}{\Gamma(2.85)} t^{1.85}-\frac{\Gamma(2)}{\Gamma(1.85)} t^{0.85}-\frac{\sqrt{\pi} \Gamma(3)}{4 \Gamma(3.5)} t^{2.5}+\frac{\sqrt{\pi} \Gamma(2)}{4 \Gamma(2.5)} t^{1.5}-\frac{e^{t+1}-3 e^{t}}{7} .
$$

In this problem the exact solution of this equation is $u(t)=t^{2}-t$. We have solved this FIDE with weakly singular kernel by using the wavelet and BPFs collocation methods. The maximum absolute error of the numerical results derived by wavelet basis and BPFs collocation method for various values of $\hat{m}$ are presented in Table 3. Similar to the previous example, the numerical results obtained by LW, CHW and SKCHW basis are more accurate in compare to othe basis. Moreover, Table 3 indicate that the LW, CHW and SKCHW have same convergence behavior as BPFs and HW have same. Computational time for different wavelet and BPFs basis with $\hat{m}=64$ are listed in Table 2. From this Table it is possible to see that the computational time of CASW is higher than other kind of basis functions and BPFs has the minimum computational time.

Table 3: Comparison of the maximum absolute error for different wavelet basis and various values of $\hat{m}$.

|  | $\hat{m}=24$ | $\hat{m}=48$ | $\hat{m}=64$ |
| :---: | :---: | :---: | :---: |
| BPFs | $2.62 \times 10^{-2}$ | $1.24 \times 10^{-2}$ | $8.41 \times 10^{-3}$ |
| HW | $1.16 \times 10^{-2}$ | $1.21 \times 10^{-2}$ | $8.82 \times 10^{-3}$ |
| LW | $2.35 \times 10^{-3}$ | $1.14 \times 10^{-3}$ | $1.14 \times 10^{-3}$ |
| CHW | $3.51 \times 10^{-3}$ | $1.16 \times 10^{-3}$ | $2.24 \times 10^{-3}$ |
| SKCHW | $3.27 \times 10^{-3}$ | $2.64 \times 10^{-3}$ | $2.11 \times 10^{-3}$ |
| CASW | $5.43 \times 10^{-2}$ | $3.11 \times 10^{-2}$ | $2.54 \times 10^{-2}$ |

Table 4: Comparison of computational time (in seconds) for different wavelet basis and $\hat{m}=64$.

|  | BPFs | HW | LW | CHW | SKCHW | CASW |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: |
| CPU time (sec) | 140.688 | 142.146 | 141.235 | 147.249 | 148.698 | 194.771 |

Example 8.3. Let us consider the following fractional order integro-differential equation with a weakly singular kernel [13]

$$
D_{*}^{\alpha} u(t)=f(t)+\int_{0}^{t} \frac{u(s) d s}{(t-s)^{\frac{1}{2}}}+\int_{0}^{1}(t+\sin (s)) u(s)
$$

where $u(0)=0$ and

$$
f(t)=2 t-\frac{\sqrt{\pi} \Gamma(3)}{2 \Gamma(3.5)} t^{2.5}-\frac{t}{3}-\cos (1)-2 \sin (1)+2 .
$$

When $\alpha=1$, the exact solution of this fractional integro-differential equation is $u(t)=t^{2}$. The proposed collocation method are used for solving this FIDE for various values of $\alpha$ and different kind wavelet basis. The maximum absolute error of numerical solutions with $\alpha=1$ are tabulated in Table 5. From this Table, we infer that numerical solutions derived by BPFs and all wavelet basis converge to the exact solution. Moreover, numerical solutions for $\alpha=0.85$ and $\alpha=0.95$ are listed in Tables 6 and 7. As it is obvious from Tables 6 and 7 the numerical solutions converge to the exact solution $u(t)=t^{2}$ as $\alpha$ is close to 1 . Table 8 displays the comparison between the computational time of BPFs and different wavelet basis for $\alpha=1$ and $\hat{m}=64$. As can be observed from this Table, the computational time of BPFs method is minimum and computational time of CASW method is higher than other kind of basis functions.

## 9. Discussion and conclusion

This paper deals with a comparitive study of wavelet collocation methods for numerical solution of fractional order integro-differential equation with a weakly singular kernel. The numerical results derived by different kind of wavelets basis are also compared with the BPFs collocation method. A comparison is made between computational time of the proposed collocation methods for BPFs and different kind of wavelet basis. The comparison of the experimental results highlighted that:

Table 5: Comparison of the maximum absolute error for different wavelet basis and various values of $\hat{m}$.

|  | $\hat{m}=24$ | $\hat{m}=48$ | $\hat{m}=64$ |
| :---: | :---: | :---: | :---: |
| BPFs | $3.34 \times 10^{-1}$ | $3.14 \times 10^{-2}$ | $1.84 \times 10^{-2}$ |
| HW | $6.84 \times 10^{-1}$ | $3.43 \times 10^{-2}$ | $2.88 \times 10^{-2}$ |
| LW | $5.77 \times 10^{-3}$ | $4.87 \times 10^{-3}$ | $2.68 \times 10^{-3}$ |
| CHW | $4.05 \times 10^{-3}$ | $1.28 \times 10^{-3}$ | $1.32 \times 10^{-3}$ |
| SKCHW | $5.69 \times 10^{-3}$ | $4.66 \times 10^{-3}$ | $2.34 \times 10^{-3}$ |
| CASW | $2.43 \times 10^{-1}$ | $7.50 \times 10^{-2}$ | $2.25 \times 10^{-2}$ |

Table 6: The numerical results derived by different wavelet basis for $\alpha=0.85$ and $\hat{m}=64$.

| $t$ | BPFs | HW | LW | CHW | SKCHW | CASW |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 0.1 | 0.075912 | 0.075912 | 0.074556 | 0.074556 | 0.074556 | 0.082991 |
| 0.3 | 0.322010 | 0.322010 | 0.314696 | 0.314696 | 0.314696 | 0.289446 |
| 0.5 | 1.402528 | 1.402528 | 1.402275 | 1.402274 | 1.402274 | 1.527805 |
| 0.7 | 1.239159 | 1.239159 | 1.254223 | 1.254223 | 1.254223 | 1.294679 |
| 0.9 | 1.995424 | 1.995424 | 2.002114 | 2.002115 | 2.002114 | 1.966650 |

Table 7: The numerical results derived by different wavelet basis for $\alpha=0.95$ and $\hat{m}=64$.

| $t$ | BPFs | HW | LW | CHW | SKCHW | CASW |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 0.1 | 0.020154 | 0.020154 | 0.019664 | 0.019664 | 0.019664 | 0.022894 |
| 0.3 | 0.131961 | 0.131961 | 0.128306 | 0.128306 | 0.128306 | 0.115236 |
| 0.5 | 0.659830 | 0.659831 | 0.659685 | 0.659685 | 0.659685 | 0.731165 |
| 0.7 | 0.618552 | 0.618552 | 0.626625 | 0.626625 | 0.626625 | 0.648190 |
| 0.9 | 1.019279 | 1.019279 | 1.022773 | 1.022773 | 1.022773 | 1.004034 |

Table 8: Comparison of computational time (in seconds) for $\alpha=1$ and $\hat{m}=64$.

|  | BPFs | HW | LW | CHW | SKCHW | CASW |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| CPU time (sec) | 155.429 | 152.397 | 162.587 | 164.239 | 170.234 | 210.537 |

1. The proposed collocation methods with BPFs and wavelet basis are simple and effective for numerical solution of fractional order integro-differential equation with a weakly singular kernel.
2. The numerical results obtained by LW, CHW and SKCHW basis are more accurate comparing with BPFs and the other kind of wavelet basis considered in this paper. In fact, being the BPFs linear functions, as expected they can capture only a first approximation of the numerical solution.
3. The presented collocation methods with LW, CHW and SKCHW have same convergence behavior as BPFs and HW have same convergence behavior.
4. The computational time of CASW is more than BPFs and other kind of wavelet basis. Moreover, the BPFs collocation method has the minimum computational time. In fact, according to theorems 5.4 and 5.5 , the operational matrices of wavelets are obtained by a matrix product with the operational matrix of BPFs thus implying a greater computational time.
5. In general, the LW collocation method is the best one for solving fractional order integrodifferential equation with a weakly singular kernel.
6. The examples given in section 8 show that, when the analytical solution is a polynomial, then Legendre polynomials and other kind of polynomial based wavelets are good methods of approximation. However in some more general case when the solution is a more general function then it would be more expedient to use different kind of wavelets more similar to the solution.

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